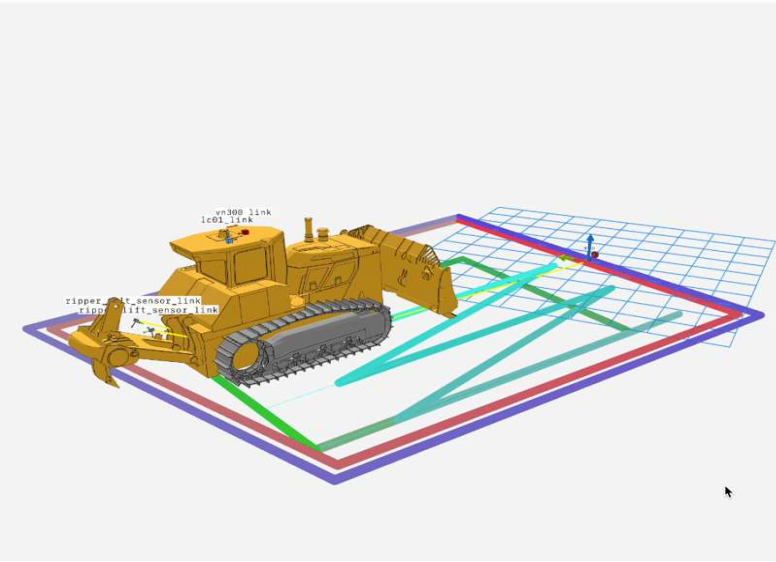




AUTONOMOUS	NONE
/bulldozer/hardw... sensor_msgs/msg/NavSatFix @ 1734500331.374000000 sec ▼ header {} frame_id: gps ▼ stamp 2024-12-18 2:35:30.727 PM JST sec 1734500130 nsec 727326895 frame_id "gps" ▼ status {} 2 keys status 2 (STATUS_GBAS_FIX) service 1 (SERVICE_GPS) latitude 34.490163251666665 longitude 133.71245863333334 altitude 42.235 position_covariance Float64Array (9) [0.00010816000000000000 2, 0, 0, 0, 0.00010816000000000000 0.00002, 0, 0, 0, 0.001730560 0.00000000031]	/bulldozer/control... jakarta_api/msg/Actuation @ 1734500331.449000000 sec locomotion 0 turn 0 ripper_up_down 0 ripper_front_back 0 blade_up_down 0 blade_left_right 0 engine_rpm_setting 0 engine_rpm_adjustment 0 brake true

/bulldozer/control...

⚙

⋮

jakarta_api/msg/Actuation @ 1734500331.449000000 sec

locomotion 0

turn 0

ripper_up_down 0

ripper_front_back 0

blade_up_down 0

blade_left_right 0

engine_rpm_setting 0

engine_rpm_adjustment 0

brake true